

Introduction to $U(1)$ Gauge Field Theory and Its Quantization

Zhang Chang-kai

Department of Physics,
Beijing Normal University

June 15, 2016

Contents

- 1 Mathematical Foundation
 - Topology and Manifold
 - Lie Group and Lie Algebra
 - Fibre Bundle
- 2 Construction of Fields
 - Construction of Background
 - Construction of Field
 - First Quantization
 - U(1) Gauge Theory
- 3 Second Quantization of U(1) Gauge Field
 - Path Integral
 - General Gauge Fixing

Contents

- 1 Mathematical Foundation
 - Topology and Manifold
 - Lie Group and Lie Algebra
 - Fibre Bundle
- 2 Construction of Fields
 - Construction of Background
 - Construction of Field
 - First Quantization
 - $U(1)$ Gauge Theory
- 3 Second Quantization of $U(1)$ Gauge Field
 - Path Integral
 - General Gauge Fixing

Definition of Topological Space

Definition from textbook

Definition

Topological space is a set X together with a subset \mathcal{T} of its power set satisfying

- 1 $\emptyset, X \in \mathcal{T}$
- 2 Closed under finite intersection
- 3 Closed under arbitrary union

Definition of Topological Space

Definition from textbook

Definition

Topological space is a set X together with a subset \mathcal{T} of its power set satisfying

- 1 $\emptyset, X \in \mathcal{T}$
- 2 Closed under finite intersection
- 3 Closed under arbitrary union

Topology is the generalization of open interval.

Definition of Topological Space

Definition from textbook

Definition

Topological space is a set X together with a subset \mathcal{T} of its power set satisfying

- 1 $\emptyset, X \in \mathcal{T}$
- 2 Closed under finite intersection
- 3 Closed under arbitrary union

Topology is the generalization of open interval.

Example

Open set of \mathbb{R}^n is defined as

$$U = \text{span}\{(a, b)\}$$

Construction of Manifold

Definition

A map f between topological spaces (X, \mathcal{T}) , (Y, \mathcal{S}) is continuous if

$$(\forall V \subset \text{img}(f) \in \mathcal{S}) f^{-1}[V] \in \mathcal{T}$$

Construction of Manifold

Definition

A map f between topological spaces (X, \mathcal{T}) , (Y, \mathcal{S}) is continuous if

$$(\forall V \subset \text{img}(f) \in \mathcal{S}) f^{-1}[V] \in \mathcal{T}$$

Definition

Topological homeomorphism is a bijection f satisfying f and f^{-1} is continuous.

Construction of Manifold

Definition

A map f between topological spaces (X, \mathcal{T}) , (Y, \mathcal{S}) is continuous if

$$(\forall V \subset \text{img}(f) \in \mathcal{S}) f^{-1}[V] \in \mathcal{T}$$

Definition

Topological homeomorphism is a bijection f satisfying f and f^{-1} is continuous.

Definition

(n -dimensional C^r) manifold is a topological space with open cover U_α satisfying

- 1 There exists homeomorphism $\psi_\alpha : U_\alpha \rightarrow V_\alpha$ ($\forall U_\alpha$)
- 2 For $U_\alpha \cap U_\beta \neq \emptyset$, composite $\psi_\beta \circ \psi_\alpha^{-1}$ is C^r .

Lie Group

Definition

Group G is a set with multiplication $\cdot : G \times G \rightarrow G$ satisfying

- 1 $(g_1g_2)g_3 = g_1(g_2g_3)$
- 2 $(\exists e) \quad ge = eg = g$
- 3 $(\forall g, \exists g^{-1}) \quad gg^{-1} = g^{-1}g = e$

Lie Group

Definition

Group G is a set with multiplication $\cdot : G \times G \rightarrow G$ satisfying

- 1 $(g_1g_2)g_3 = g_1(g_2g_3)$
- 2 $(\exists e) \quad ge = eg = g$
- 3 $(\forall g, \exists g^{-1}) \quad gg^{-1} = g^{-1}g = e$

Definition

Lie Group G is both a group and a n -dimensional smooth manifold with multiplication \cdot and inverse -1 is smooth.

Lie Group

Definition

Group G is a set with multiplication $\cdot : G \times G \rightarrow G$ satisfying

- 1 $(g_1g_2)g_3 = g_1(g_2g_3)$
- 2 $(\exists e) \quad ge = eg = g$
- 3 $(\forall g, \exists g^{-1}) \quad gg^{-1} = g^{-1}g = e$

Definition

Lie Group G is both a group and a n -dimensional smooth manifold with multiplication \cdot and inverse -1 is smooth.

This assigns a group with a coordinate system.

Lie Group

Definition

Group G is a set with multiplication $\cdot : G \times G \rightarrow G$ satisfying

- 1 $(g_1g_2)g_3 = g_1(g_2g_3)$
- 2 $(\exists e) \quad ge = eg = g$
- 3 $(\forall g, \exists g^{-1}) \quad gg^{-1} = g^{-1}g = e$

Definition

Lie Group G is both a group and a n -dimensional smooth manifold with multiplication \cdot and inverse -1 is smooth.

This assigns a group with a coordinate system.

Definition

Left transformation L_g is a map $L_g : h \mapsto gh$.

Lie Algebra

Definition

Vector field \bar{A} is left invariant if $L_{g*}\bar{A} = \bar{A}$.

Lie Algebra

Definition

Vector field \bar{A} is left invariant if $L_{g*}\bar{A} = \bar{A}$.

Definition

Lie bracket of vector space V is a map $V \times V \rightarrow V$ satisfying

- 1 $[A, B] = -[B, A]$
- 2 $[A, [B, C]] + [C, [A, B]] + [B, [C, A]] = 0$

A vector space with Lie bracket forms a Lie Algebra.

Lie Algebra

Definition

Vector field \bar{A} is left invariant if $L_{g*}\bar{A} = \bar{A}$.

Definition

Lie bracket of vector space V is a map $V \times V \rightarrow V$ satisfying

- 1 $[A, B] = -[B, A]$
- 2 $[A, [B, C]] + [C, [A, B]] + [B, [C, A]] = 0$

A vector space with Lie bracket forms a Lie Algebra.

Definition

Define

$$[A, B] = [\bar{A}, \bar{B}]_e$$

with commutator of vectors in Lie Group G . This forms the Lie Algebra of Lie Group G .

Principal Bundle

Definition

Left (right) action of manifold K is a map $L(R) : K \times G \rightarrow K$ satisfying

- 1 $L(R)_g$ is a diffeomorphism.
- 2 $L_{gh} = L_g L_h$ and $R_{gh} = R_h R_g$

Principal Bundle

Definition

Left (right) action of manifold K is a map $L(R) : K \times G \rightarrow K$ satisfying

- 1 $L(R)_g$ is a diffeomorphism.
- 2 $L_{gh} = L_g L_h$ and $R_{gh} = R_h R_g$

Definition

Principal bundle is constructed with a bundle manifold P , a base manifold M and a structure group G , satisfying

- 1 G has a free right action on P
- 2 Exists a smooth onto projection map $\pi : P \rightarrow M$ satisfying $\pi^{-1}[\pi[p]] = \{pg, g \in G\}$
- 3 Exists a local trivialization $T_U : p \mapsto (\pi(p), S_U(p)) \in U \times G$

Associated Bundle

Definition

Fibre bundle associated to principal bundle P is a set $P \times F / \sim$ with

- 1 Left action $\chi_g(f) = gf$
- 2 Induced free right action $\xi_g(p, f) = (pg, g^{-1}f)$
- 3 Equivalence relation $(p, f) \sim (pg, g^{-1}f)$

Cross section, connection and curvature

Definition

Smooth map $\sigma : U \rightarrow P$ is a cross section if

$$\pi(\sigma(x)) = x$$

Cross section, connection and curvature

Definition

Smooth map $\sigma : U \rightarrow P$ is a cross section if

$$\pi(\sigma(x)) = x$$

Definition

Connection is a smooth \mathfrak{g} -valued 1-form ω_U for each local trivialization T_U . And if the transition map of T_U and T_V is g_{uv} , there is

$$\omega_V = g_{uv}^{-1} \omega_U g_{uv} + g_{uv}^{-1} dg_{uv}$$

Cross section, connection and curvature

Definition

Smooth map $\sigma : U \rightarrow P$ is a cross section if

$$\pi(\sigma(x)) = x$$

Definition

Connection is a smooth \mathfrak{g} -valued 1-form ω_U for each local trivialization T_U . And if the transition map of T_U and T_V is g_{uv} , there is

$$\omega_V = g_{uv}^{-1} \omega_U g_{uv} + g_{uv}^{-1} dg_{uv}$$

Definition

Curvature of connection is defined as

$$\Omega = d\omega + \frac{1}{2}[\omega, \omega]$$

Contents

- 1 Mathematical Foundation
 - Topology and Manifold
 - Lie Group and Lie Algebra
 - Fibre Bundle
- 2 Construction of Fields
 - Construction of Background
 - Construction of Field
 - First Quantization
 - U(1) Gauge Theory
- 3 Second Quantization of U(1) Gauge Field
 - Path Integral
 - General Gauge Fixing

Background Construction

Definition

Base Manifold M :

4-dimensional connected Hausdorff second-countable orientable
time-orientable framed smooth manifold

Background Construction

Definition

Base Manifold M :

4-dimensional connected Hausdorff second-countable orientable
time-orientable framed smooth manifold

Definition

Structure Group G : Matrix Lie Group

Background Construction

Definition

Base Manifold M :

4-dimensional connected Hausdorff second-countable orientable
time-orientable framed smooth manifold

Definition

Structure Group G : Matrix Lie Group

Definition

Principal Bundle P :

Trivial principal bundle $P = M \times G$

Background Construction

Definition

Base Manifold M :

4-dimensional connected Hausdorff second-countable orientable time-orientable framed smooth manifold

Definition

Structure Group G : Matrix Lie Group

Definition

Principal Bundle P :

Trivial principal bundle $P = M \times G$

Definition

Associated Bundle Q :

$Q = (P \times F) / \sim$ with F a Banach space

Background Construction

Definition

Base Manifold M :

4-dimensional connected Hausdorff second-countable orientable
time-orientable framed smooth manifold

Definition

Structure Group G : Matrix Lie Group

Definition

Principal Bundle P :

Trivial principal bundle $P = M \times G$

Definition

Associated Bundle Q :

$Q = (P \times F) / \sim$ with F a Banach space

Field Construction

Definition

Gauge is the cross section of principal bundle.

Field Construction

Definition

Gauge is the cross section of principal bundle.

Definition

Field ψ is the cross section of associated bundle.

Field Construction

Definition

Gauge is the cross section of principal bundle.

Definition

Field ψ is the cross section of associated bundle.

Definition

Gauge field is a connection of principal bundle

$$\omega_\mu = eA_\mu$$

Field Construction

Definition

Gauge is the cross section of principal bundle.

Definition

Field ψ is the cross section of associated bundle.

Definition

Gauge field is a connection of principal bundle

$$\omega_\mu = eA_\mu$$

Definition

Gauge field strength is the curvature of principal bundle

$$\Omega_{\mu\nu} = eF_{\mu\nu}$$

First Quantization

Definition

First quantization is to construct the Lagrangian of matter field as

$$\mathcal{L} = -i\bar{\psi}(\gamma^\mu \nabla_\mu + m)\psi$$

where ∇_μ is the covariant derivative of associated bundle

$$\nabla_\mu = \partial_\mu + \omega_\mu$$

First Quantization

Definition

First quantization is to construct the Lagrangian of matter field as

$$\mathcal{L} = -i\bar{\psi}(\gamma^\mu \nabla_\mu + m)\psi$$

where ∇_μ is the covariant derivative of associated bundle

$$\nabla_\mu = \partial_\mu + \omega_\mu$$

Definition

Construct the kinematic term as

$$\mathcal{L} = -\frac{1}{4}\text{tr}(F_{\mu\nu} \cdot F^{\mu\nu})$$

U(1) Gauge Theory

Principal Bundle: $M \times U(1)$

U(1) Gauge Theory

Principal Bundle: $M \times U(1)$

Left action $\chi_g(\psi) = \exp\{-iq\theta\}\psi$ Usually take $q = 1$

U(1) Gauge Theory

Principal Bundle: $M \times U(1)$

Left action $\chi_g(\psi) = \exp\{-iq\theta\}\psi$ Usually take $q = 1$

Representation Group $\hat{G} = G = U(1)$

U(1) Gauge Theory

Principal Bundle: $M \times U(1)$

Left action $\chi_g(\psi) = \exp\{-iq\theta\}\psi$ Usually take $q = 1$

Representation Group $\hat{G} = G = U(1)$

Thus, the covariant derivative

$$\nabla_\mu \psi = \partial_\mu \psi - ieA_\mu \psi$$

U(1) Gauge Theory

Principal Bundle: $M \times U(1)$

Left action $\chi_g(\psi) = \exp\{-iq\theta\}\psi$ Usually take $q = 1$

Representation Group $\hat{G} = G = U(1)$

Thus, the covariant derivative

$$\nabla_\mu \psi = \partial_\mu \psi - ieA_\mu \psi$$

Matter term

$$\mathcal{L} = -i\bar{\psi}(\gamma^\mu \partial_\mu + m)\psi$$

Gauge term

$$\mathcal{L} = -\frac{1}{4}\text{tr}(F_{\mu\nu} \cdot F^{\mu\nu})$$

Interaction term

$$\mathcal{L} = -ie\bar{\psi}\gamma^\mu A_\mu \psi$$

Contents

- 1 Mathematical Foundation
 - Topology and Manifold
 - Lie Group and Lie Algebra
 - Fibre Bundle
- 2 Construction of Fields
 - Construction of Background
 - Construction of Field
 - First Quantization
 - U(1) Gauge Theory
- 3 Second Quantization of U(1) Gauge Field
 - Path Integral
 - General Gauge Fixing

Path Integral of Gauge Field

The original path integral should be

$$W[J] = \int [\mathcal{D}\omega] \exp\left\{i \int \varepsilon \left(-\frac{1}{4} F_{\mu\nu} \cdot F_{\mu\nu} + J^\mu \cdot \omega_\mu\right)\right\}$$

Path Integral of Gauge Field

The original path integral should be

$$W[J] = \int [\mathcal{D}\omega] \exp\left\{i \int \varepsilon \left(-\frac{1}{4} F_{\mu\nu} \cdot F_{\mu\nu} + J^\mu \cdot \omega_\mu\right)\right\}$$

However, we find that this is uncertain since the gauge freedom makes the four components of connection not all independent.

Path Integral of Gauge Field

The original path integral should be

$$W[J] = \int [\mathcal{D}\omega] \exp\left\{i \int \varepsilon \left(-\frac{1}{4} F_{\mu\nu} \cdot F_{\mu\nu} + J^\mu \cdot \omega_\mu\right)\right\}$$

However, we find that this is uncertain since the gauge freedom makes the four components of connection not all independent. Notice that the electromagnetic wave is a transverse wave. Thus we introduce temporal gauge fixing

$$W[J] = \int [\mathcal{D}\omega \delta(\omega_0)] \exp\left\{i \int \varepsilon \left(-\frac{1}{4} F_{\mu\nu} \cdot F_{\mu\nu} + J^\mu \cdot \omega_\mu\right)\right\}$$

Path Integral of Gauge Field

The original path integral should be

$$W[J] = \int [\mathcal{D}\omega] \exp\left\{i \int \varepsilon \left(-\frac{1}{4} F_{\mu\nu} \cdot F_{\mu\nu} + J^\mu \cdot \omega_\mu\right)\right\}$$

However, we find that this is uncertain since the gauge freedom makes the four components of connection not all independent. Notice that the electromagnetic wave is a transverse wave. Thus we introduce temporal gauge fixing

$$W[J] = \int [\mathcal{D}\omega \delta(\omega_0)] \exp\left\{i \int \varepsilon \left(-\frac{1}{4} F_{\mu\nu} \cdot F_{\mu\nu} + J^\mu \cdot \omega_\mu\right)\right\}$$

However, this will destroy the Lorentz invariance.

General Gauge Fixing

Consider Lorentz invariant gauge fixing

$$f(\omega) - C = 0$$

General Gauge Fixing

Consider Lorentz invariant gauge fixing

$$f(\omega) - C = 0$$

Introduce Fadeev-Popov determinant

$$\Sigma_f^{-1} \equiv \int [\mathcal{D}g] \delta(f(\omega) - C)$$

General Gauge Fixing

Consider Lorentz invariant gauge fixing

$$f(\omega) - C = 0$$

Introduce Fadeev-Popov determinant

$$\Sigma_f^{-1} \equiv \int [\mathcal{D}g] \delta(f(\omega) - C)$$

Remarks. The strictness of this determinant is still under investigation.

General Gauge Fixing

Consider Lorentz invariant gauge fixing

$$f(\omega) - C = 0$$

Introduce Fadeev-Popov determinant

$$\Sigma_f^{-1} \equiv \int [\mathcal{D}g] \delta(f(\omega) - C)$$

Remarks. The strictness of this determinant is still under investigation. Adding $\Sigma_f \Sigma_f^{-1}$ into the path integral and get

$$W[J] = \int [\mathcal{D}\omega \mathcal{D}g \delta(f(\omega) - C)] \Sigma_f \exp\left\{i \int \varepsilon \left(-\frac{1}{4} F_{\mu\nu} \cdot F_{\mu\nu} + J^\mu \cdot \omega_\mu\right)\right\}$$

General Gauge Fixing

For Abelian gauge theory, f can be chosen $f \sim \omega$ and thus Σ_f finally turn out to be a constant \rightarrow normalization factor.

General Gauge Fixing

For Abelian gauge theory, f can be chosen $f \sim \omega$ and thus Σ_f finally turn out to be a constant \rightarrow normalization factor.

By adding a Gaussian factor of C

$$\int [\mathcal{D}C] \exp\left\{-\frac{i}{2\alpha} \int \varepsilon C \cdot C\right\}$$

and integrate C , there will be

$$W[J] = \int [\mathcal{D}\omega] \exp\left\{i \int \varepsilon \left(-\frac{1}{4} F_{\mu\nu} \cdot F_{\mu\nu} - \frac{1}{2\alpha} f \cdot f + J^\mu \cdot \omega_\mu\right)\right\}$$

This is the desired result.

Thanks!